

# Package ‘gamlss.spatial’

October 15, 2023

**Type** Package

**Title** Spatial Terms in Generalized Additive Models for Location Scale and Shape Models

**Version** 3.0-2

**Date** 2023-10-14

**Description** It allows us to fit Gaussian Markov Random Field within the Generalized Additive Models for Location Scale and Shape algorithms.

**License** GPL-2 | GPL-3

**URL** <https://www.gamlss.com/>

**Depends** R (>= 2.15.0), gamlss.dist, gamlss (>= 4.2-7), gamlss.add, spam, mgcv

**Imports** stats, grDevices, graphics, methods

**Repository** CRAN

**NeedsCompilation** no

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gamlss.spatial-package

*Spatial Terms in Generalized Additive Models for Location Scale and Shape Models*

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## Description

It allows us to fit Gaussian Markov Random Field within the Generalized Additive Models for Location Scale and Shape algorithms.

## Details

The DESCRIPTION file:

```
Package:          gamlss.spatial
Type:             Package
Title:            Spatial Terms in Generalized Additive Models for Location Scale and Shape Models
Version:          3.0-2
Date:             2023-10-14
Authors@R:        c(person("Fernanda", "De Bastiani", role = c("aut", "cre", "cph"), email = "fernandadebastiani@gmail.c
Description:      It allows us to fit Gaussian Markov Random Field within the Generalized Additive Models for Location
License:          GPL-2 | GPL-3
URL:              https://www.gamlss.com/
Depends:          R (>= 2.15.0), gamlss.dist, gamlss (>= 4.2-7), gamlss.add, spam, mgcv
Imports:          stats, grDevices, graphics, methods
Repository:       CRAN
NeedsCompilation: no
Packaged:         2015-07-09 13:32:17 UTC; stasinom
Author:           Fernanda De Bastiani [aut, cre, cph], Mikis Stasinopoulos [aut], Robert Rigby [aut]
Maintainer:       Fernanda De Bastiani <fernandadebastiani@gmail.com>
RoxygenNote:     5.0.1
```

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gamlss.gmrf        Gaussian Markov Random Field fitting within
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gamlss.spatial-package Spatial Terms in Generalized Additive Models
                  for Location Scale and Shape Models
```

## Author(s)

Fernanda De Bastiani [aut, cre, cph], Mikis Stasinopoulos [aut], Robert Rigby [aut]

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## References

De Bastiani, F. Rigby, R. A., Stasinopoulos, D. M., Cysneiros, A. H. M. A. and Uribe-Opazo, M. A. (2016) Gaussian Markov random spatial models in GAMLSS. *Journal of Applied Statistics*, pp 1-19.

Rigby, R. A. and Stasinopoulos D. M. (2005). Generalized additive models for location, scale and shape,(with discussion), *Appl. Statist.*, **54**, part 3, pp 507-554.

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Rue and Held (2005) *Gaussian markov random fields: theory and applications*, Chapman & Hall, USA.

Stasinopoulos D. M. Rigby R.A. (2007) Generalized additive models for location scale and shape (GAMLSS) in R. *Journal of Statistical Software*, Vol. **23**, Issue 7, Dec 2007, <https://www.jstatsoft.org/v23/i07/>.

Stasinopoulos D. M., Rigby R.A., Heller G., Voudouris V., and De Bastiani F., (2017) *Flexible Regression and Smoothing: Using GAMLSS in R*, Chapman and Hall/CRC.

(see also <https://www.gamlss.com/>).

## Examples

```
library(mgcv)
data(columb)
data(columb.polys)
m1 <- MRFA(columb$crime, columb$district, polys=columb.polys)
draw.polys(columb.polys, m1)
```

---

draw.polys

*Additional supporting functions for random Markov fields*

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## Description

This set of functions were useful in the past to get information and to plot maps but somehow now seem redundant.

## Usage

```
draw.polys(polys, object = NULL, scheme = NULL,
           swapcolors = FALSE, n.col = 100, ...)
polys2nb(polys)
nb2prec(neighbour, x, area=NULL)
polys2polys(object, neighbour.nb)
nb2nb(neighbour.nb)
```

**Arguments**

polys	an object containing the polygon information for the area
object	are either the values to plot in the draw.polys() function or a polygons information for a shape file for function polys2polys
scheme	scheme of colours to use, it can be "heat", "rainbow", "terrain", "topo", "cm" or any colour
swapcolors	to reverse the colours, it just work for "heat", "rainbow", "terrain", "topo", "cm" options
n.col	range for the colours
neighbour.nb	neighbour information for a shape file for function nb2nb
neighbour	the neighbour information, and if the neighbour is from S4 shape file than use nb2nb to transfer it to the appropriate neighbour for MRF(), MRFA(), mrf() and mrfa().
x	the factor defining the areas
area	all possible areas involved
...	for extra options

**Details**

draw.polys() plots the fitted values of fitted MRF object.

polys2nb() gets the neighbour information from the polygons.

nb2prec() creates the precision matrix from the neighbour information.

polys2polys() transforms a shape file polygons (S4 object) to the polygons required form for the functions MRF() and MRFA().

nb2nb() transforms from a shape file neighbour (S4 object) to the neighbour required form for functions MRF().

**Value**

The draw.polys() produces a plot while the rest of the functions produce required object for fitting or plotting.

**Author(s)**

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**References**

De Bastiani, F. Rigby, R. A., Stasinopoulos, D. M., Cysneiros, A. H. M. A. and Uribe-Opazo, M. A. (2016) Gaussian Markov random spatial models in GAMLSS. *Journal of Applied Statistics*, pp 1-19.

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Stasinopoulos D. M. Rigby R.A. (2007) Generalized additive models for location scale and shape (GAMLSS) in R. *Journal of Statistical Software*, Vol. **23**, Issue 7, Dec 2007, <https://www.jstatsoft.org/v23/i07/>.

Stasinopoulos D. M., Rigby R.A., Heller G., Voudouris V., and De Bastiani F., (2017) *Flexible Regression and Smoothing: Using GAMLSS in R*, Chapman and Hall/CRC.

(see also <https://www.gamlss.com/>).

### See Also

[MRF](#), [MRFA](#)

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gamlss.gmrf

*Gaussian Markov Random Field fitting within GAMLSS*

---

### Description

The function `gmrf()` can be used to fit Markov Random Field additive terms within GAMLSS.

### Usage

```
gamlss.gmrf(x, y, w, xeval = NULL, ...)
gmrf(x, precision = NULL, neighbour = NULL, polys = NULL,
      area = NULL, adj.weight = 1000, df = NULL, lambda =
      NULL, start = 10, method = c("Q", "A"), control =
      gmrf.control(...), ...)
```

### Arguments

<code>x</code>	a factor containing the areas
<code>precision</code>	the precision matrix if set
<code>neighbour</code>	an object containing the neighbour information for the area if set
<code>polys</code>	the polygon information if set
<code>area</code>	this argument is here to allow more areas than the levels of the factor <code>x</code> , see example below
<code>adj.weight</code>	a value to adjust the iterative weight if necessary
<code>df</code>	degrees of freedom for fitting if required, only for <code>method="A"</code>
<code>lambda</code>	The smoothing parameter <code>lambda</code> if known, only for <code>method="A"</code>
<code>start</code>	starting value for the smoothing parameter <code>lambda</code>

method	"Q" for Q-function, or "A" for alternating method
y	working response variable
w	iterative weights
xeval	whether to predict or not
control	to be use for some of the argument of MRF().
...	for extra arguments

### Details

The function `gmrf()` is to support the function `MRF()` and `MRFA()` within GAMLSS. It is intended to be called within a GAMLSS formula. The function `gmrf()` is not intended to be used directly. It is calling the function `MRFA()` and `MRF()` within the GAMLSS fitting algorithm. The results using the option `method="Q"` or `method="A"` should produce identical results.

### Value

a fitted `gamlss` object

### Author(s)

Fernanda De Bastiani, Mikis Stasinopoulos, Robert Rigby and Vlasios Voudouris.

Maintainer: Fernanda <fernandadebastiani@gmail.com>

### References

De Bastiani, F. Rigby, R. A., Stasinopoulos, D. M., Cysneiros, A. H. M. A. and Uribe-Opazo, M. A. (2016) Gaussian Markov random spatial models in GAMLSS. *Journal of Applied Statistics*, pp 1-19.

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(see also <https://www.gamlss.com/>).

### See Also

[MRF](#), [MRFA](#)

**Examples**

```

library(gamlss)
library(mgcv)
data(columb)
data(columb.polys)
vizinhos=polys2nb(columb.polys)
precisionC <- nb2prec(vizinhos,x=columb$district)
# MRFA
m1<- gamlss(crime~ gmrfd(district, polys=columb.polys, method="Q"), data=columb)
m2<- gamlss(crime~ gmrfd(district, polys=columb.polys, method="A"), data=columb)
AIC(m1,m2, k=0)
draw.polys(columb.polys, getSmo(m2), scheme="topo")

```

MRF

*Markov Random Fields Fitting Functions***Description**

The functions `MRF()` and `MRFA()` fit a Gaussian Markov Random Fields (MRF) model. They are used by the functions `mrf()` and `mrfa()` respectively to fit a MRF additive term within GAMLSS

**Usage**

```

MRF(y, x, precision = NULL, neighbour = NULL, polys = NULL,
     area = NULL, weights = rep(1, length(y)), sig2e = 1,
     sig2b = 1, sig2e.fix = FALSE,
     sig2b.fix = FALSE, penalty = FALSE,
     delta = c(0.01, 0.01), shift = c(0, 0))

```

```

MRFA(y, x, precision = NULL, neighbour = NULL, polys = NULL,
      area = NULL, weights = rep(1, length(y)),
      lambda = NULL, df = NULL, start = 10)

```

**Arguments**

<code>y</code>	response variable
<code>x</code>	a factor containing the areas
<code>precision</code>	the precision matrix if set
<code>neighbour</code>	an object containing the neighbour information for the area if set
<code>polys</code>	the polygon information if set
<code>area</code>	this argument is here to allow more areas than the levels of the factor <code>x</code> , see example below.
<code>weights</code>	prior weights
<code>sig2e</code>	starting values for the error variance
<code>sig2b</code>	starting values for the random field variance

sig2e.fix	whether sig2e is fixed in the fitting, default equals FALSE
sig2b.fix	whether sig2B is fixed in the fitting, default equals FALSE
penalty	whether quadratic penalty is required to help convergence in for flat likelihoods, this is equivalent of putting a normal prior distribution for the log-sigmas e.g. $\text{logsig2e} \sim N(\text{shift}, 1/\text{delta})$
delta	the precision of the prior
shift	the mean of the prior
lambda	smoothing parameter for MRFA function
start	starting value for the smoothing parameter lambda for MRFA function
df	for fixing the degrees of freedom (only in MRFA())

### Details

There are two functions for fitting Markov random fields: i) `MRF()` which uses the Q-function (marginal likelihood) for estimating the sig2e and sig2b parameters and ii) `MRFA()` which estimates the smoothing parameter  $\lambda = \text{sig2e}/\text{sig2b}$  using the "alternating" method.

### Value

a fitted MRF object

### Author(s)

Fernanda De Bastiani, Mikis Stasinopoulos, Robert Rigby and Vlasios Voudouris.

Maintainer: Fernanda <fernandadebastiani@gmail.com>

### References

De Bastiani, F. Rigby, R. A., Stasinopoulos, D. M., Cysneiros, A. H. M. A. and Uribe-Opazo, M. A. (2016) Gaussian Markov random spatial models in GAMLSS. *Journal of Applied Statistics*, pp 1-19.

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(see also <https://www.gamlss.com/>).



**See Also**[mrf](#)**Examples**

```

library(mgcv)
data(columb)
data(columb.polys)
vizinhos=polys2nb(columb.polys)
precisionC <- nb2prec(vizinhos,x=columb$district)
# MRFA
m1<-MRFA(columb$crime, columb$district, polys=columb.polys)
m11<-MRFA(columb$crime, columb$district, precision=precisionC)
m12<-MRFA(columb$crime, columb$district, neighbour=vizinhos)
draw.polys(columb.polys, m12, scheme="heat",swapcolors=TRUE)
## Not run:
# MRF
m2<-MRF(columb$crime, columb$district, polys=columb.polys)
m21<-MRF(columb$crime, columb$district, precision=precisionC)
m22<-MRF(columb$crime, columb$district, neighbour=vizinhos)
AIC(m1, m11,m12,m2, m21, m22, k=0)
draw.polys(columb.polys, m12, scheme="heat",swapcolors=TRUE)
# removing one area
columb2 <- columb[-5,]
# creating new precision matrix
precisionC2 <- nb2prec(vizinhos,x=columb$district,area=columb$district)
# MRFA
# new data but declaring area
m11<-MRFA(columb2$crime, columb2$district, polys=columb.polys, area=columb$district)
# new data old polys
m112<-MRFA(columb2$crime, columb2$district, polys=columb.polys)
# new data old precision old area
m111<-MRFA(columb2$crime, columb2$district, precision=precisionC,area=columb$district)
# new data old neighbour old area
m121<-MRFA(columb2$crime, columb2$district, neighbour=vizinhos,area=columb$district)
# new data new precision old area
m113<-MRFA(columb2$crime, columb2$district, precision=precisionC2,area=columb$district)
AIC(m11,m112,m111,m121,m113, k=0)
m11<-MRFA(columb2$crime, columb2$district, polys=columb.polys, area=columb$district)
# new data old polys
m112<-MRFA(columb2$crime, columb2$district, polys=columb.polys)
# new data old precision old area
m111<-MRFA(columb2$crime, columb2$district, precision=precisionC,area=columb$district)
# new data old neighbour old area
m121<-MRFA(columb2$crime, columb2$district, neighbour=vizinhos,area=columb$district)
# new data new precision old area
m113<-MRFA(columb2$crime, columb2$district, precision=precisionC2,area=columb$district)
AIC(m11,m112,m111,m121,m113, k=0)
draw.polys(columb.polys, fitted(m11))

## End(Not run)

```

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